

## Demo 4: Discrete Systems with Random Elements

In this demo we will examine what happens when random elements are introduced into a second order discrete system. To see that, we will consider the following system of difference equations

$$x_1(k+1) = -0.5x_1(k) + a(k)x_2(k)$$

$$x_2(k+1) = b(k)x_1(k) - 0.7x_2(k)$$

where pair  $(a(k), b(k))$  is *randomly* chosen in each step from  $(-0.25, 0.75)$ ,  $(0.5, 0.5)$  and  $(0.75, -0.5)$ . One way to make such a choice involves Scilab function

`w=rand()`

which produces a random number  $w$  between 0 and 1. If  $w \leq 0.33$ , we will set  $a(k) = -0.25$  and  $b(k) = 0.75$ . If it turns out that  $0.33 < w \leq 0.66$ ,  $a(k)$  and  $b(k)$  will be chosen as  $a(k) = b(k) = 0.5$  and if  $0.66 < w \leq 1$ , these coefficients will take on values  $a(k) = 0.75$  and  $b(k) = -0.5$ .

The file `dem4.sci` shown below (which describes the right hand side of our equation) makes use of this simple procedure. In this function, the input parameters `q1`, `q2`, and `q3` correspond to vectors  $q_1 = [-0.25; 0.75]$ ,  $q_2 = [0.5; 0.5]$  and  $q_3 = [0.75; -0.5]$  from which the pair  $(a(k), b(k))$  is chosen.

```
function y=dem4(t,x,q1,q2,q3)
    w=rand();
    if w<=0.33 then
        a=q1(1);
        b=q1(2);
    elseif (w>0.33)&(w<=0.66)
        a=q2(1);
        b=q2(2);
    else
        a=q3(1);
        b=q3(2);
    end
    y(1)=-0.5*x(1)+a*x(2);
    y(2)=b*x(1)-0.7*x(2);
endfunction
```

To solve this system with initial condition  $x(0) = [1; 1]$  and  $k_0 = 0$  for  $k = 0, 1, 2, \dots, 50$ , you

will need to type the following sequence of commands:

```
q1=[-0.25;0.75];
q2=[0.5;0.5];
q3=[0.75;-0.5];
x0=[1;1];
k0=0;
kvect=0:1:50;
y=ode("discrete",x0,k0,kvect,list(dem4,q1,q2,q3));
```

Since

$$y = \begin{bmatrix} x_1(0) & x_1(1) & x_1(2) & \dots & x_1(49) & x_1(50) \\ x_2(0) & x_2(1) & x_2(2) & \dots & x_2(49) & x_2(50) \end{bmatrix}$$

we can extract  $x_1(k)$  and  $x_2(k)$  using commands

```
x1=y(1,:);
```

and

```
x2=y(2,:);
```

respectively.

To plot the obtained sequences, enter

```
plot(kvect,x1,'.',kvect,x1)
```

and

```
plot(kvect,x2,'.',kvect,x2)
```

The resulting graphs are shown in Figs. 1 and 2.

Note that solving this equation again will *not* produce the same sequence, even if the initial conditions remain unchanged. This is due to the fact that the choice between  $q_1$ ,  $q_2$  and  $q_3$  is made *randomly*, and is therefore different every time we solve the equation. Figs. 3 and 4 illustrate what I obtained after running this program for a second time (your results will undoubtedly be different).

Figure 1

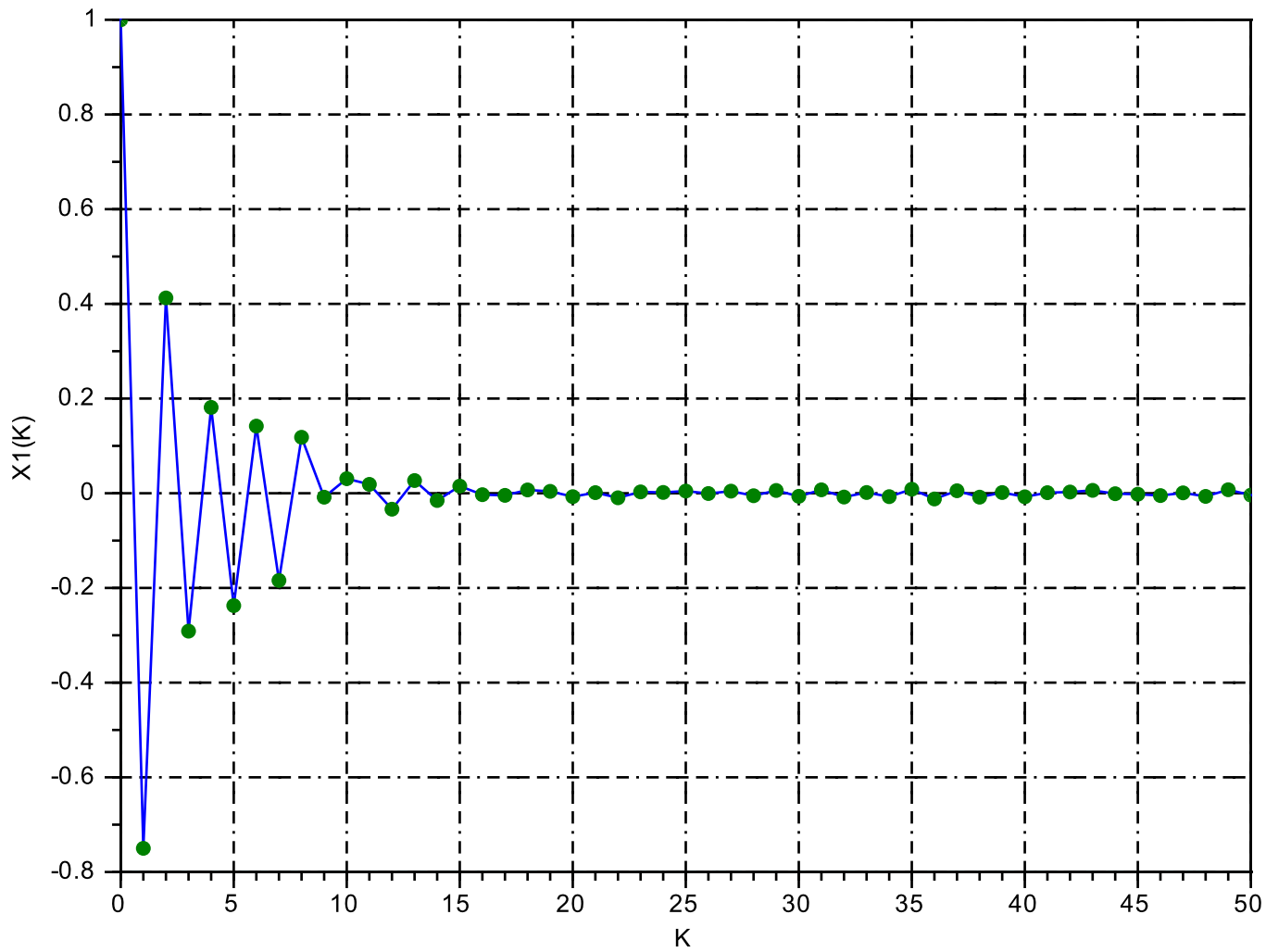


Figure 2

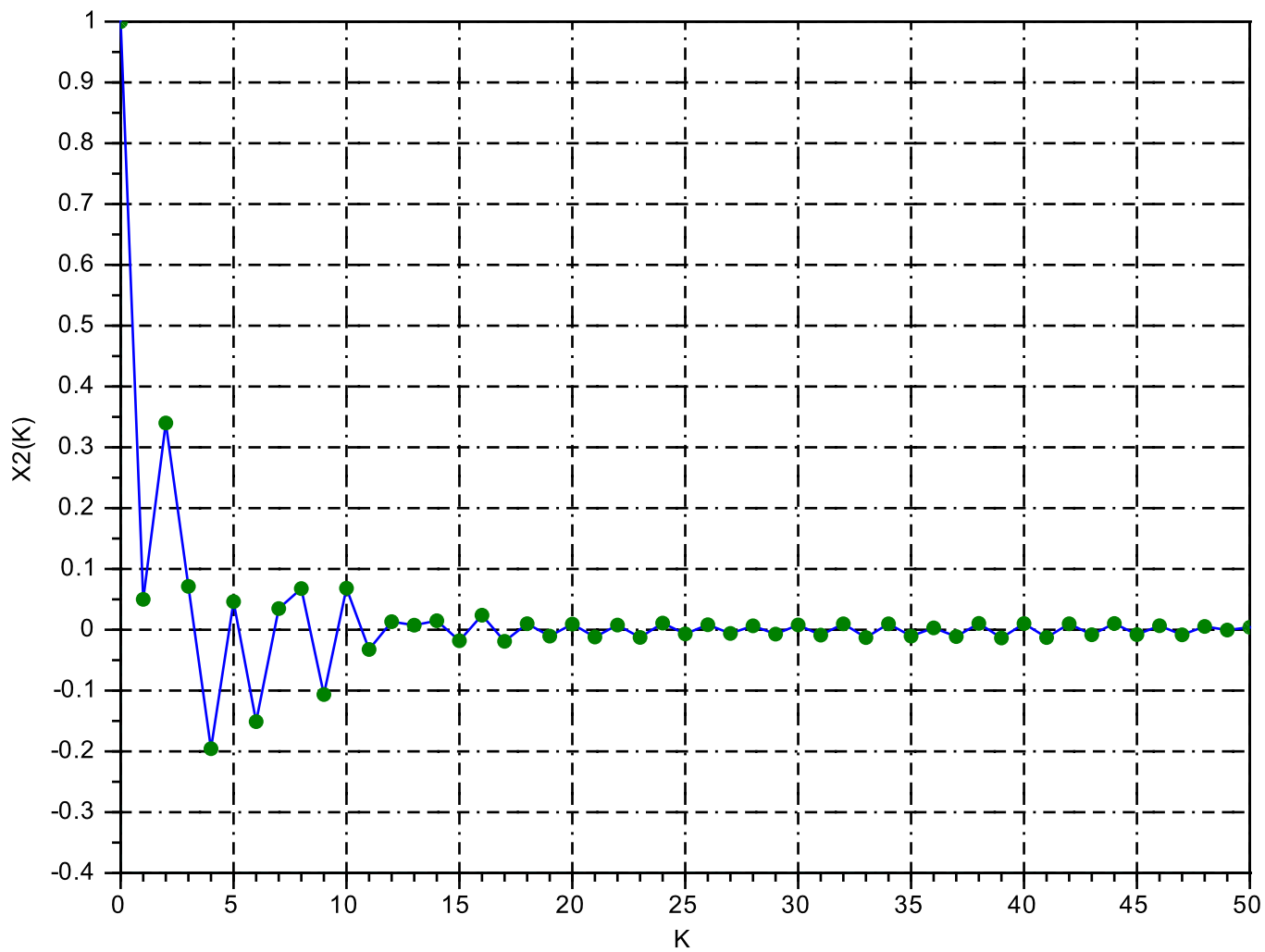


Figure 3

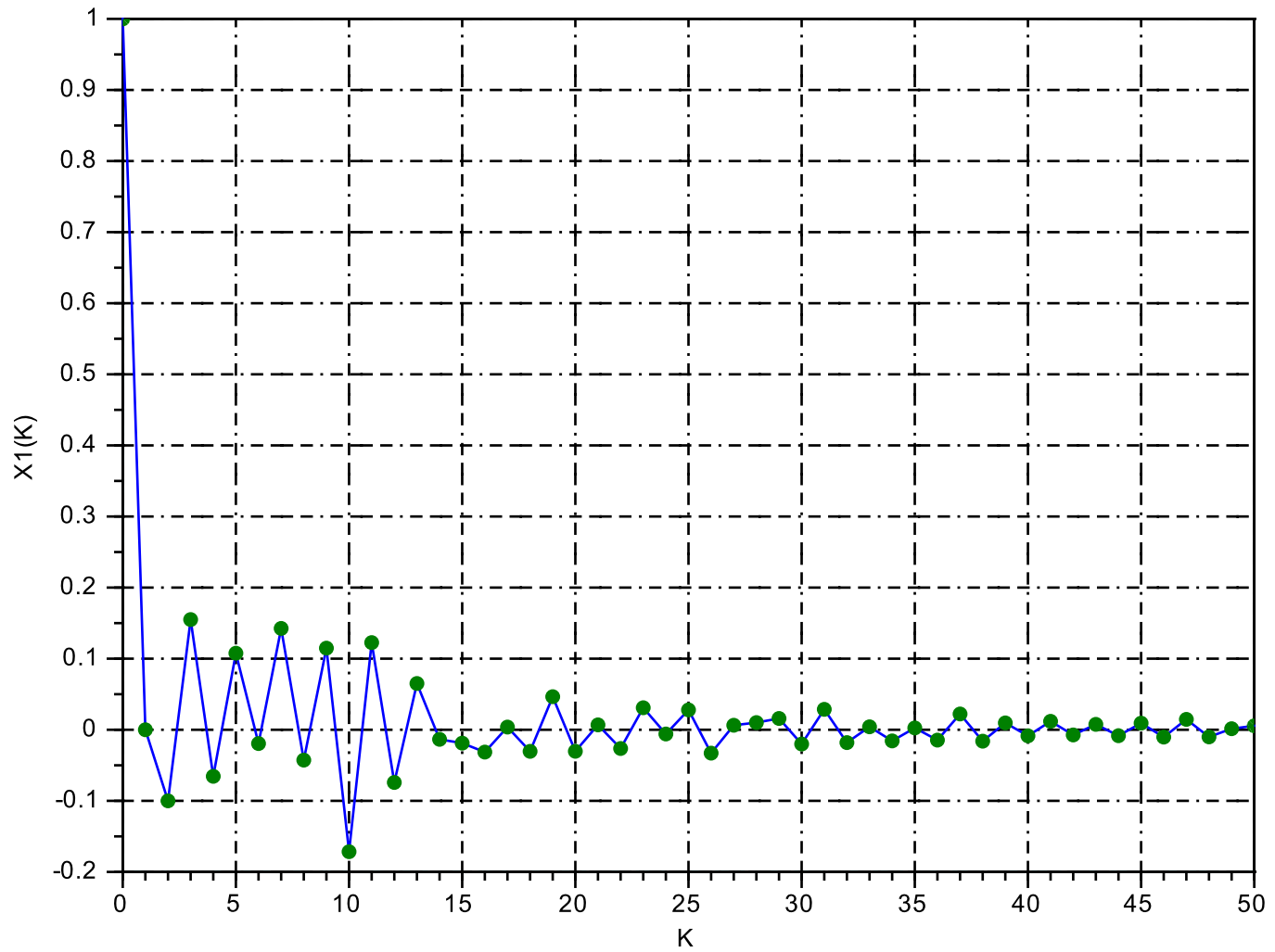


Figure 4

