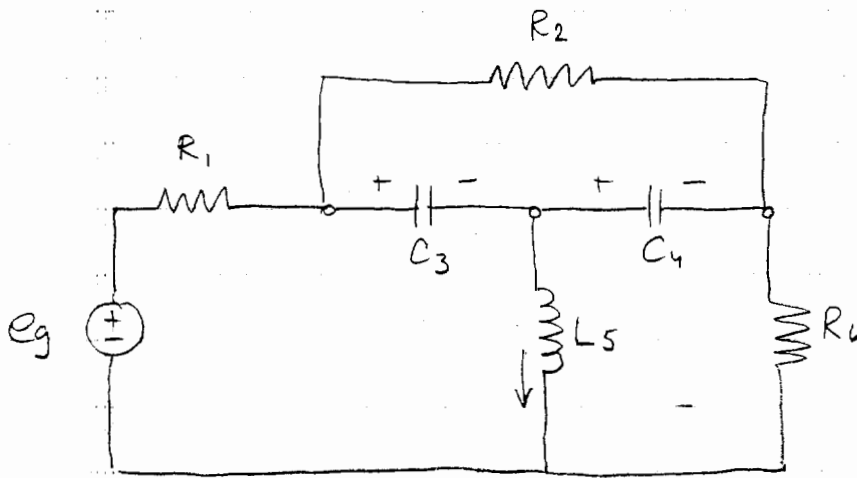


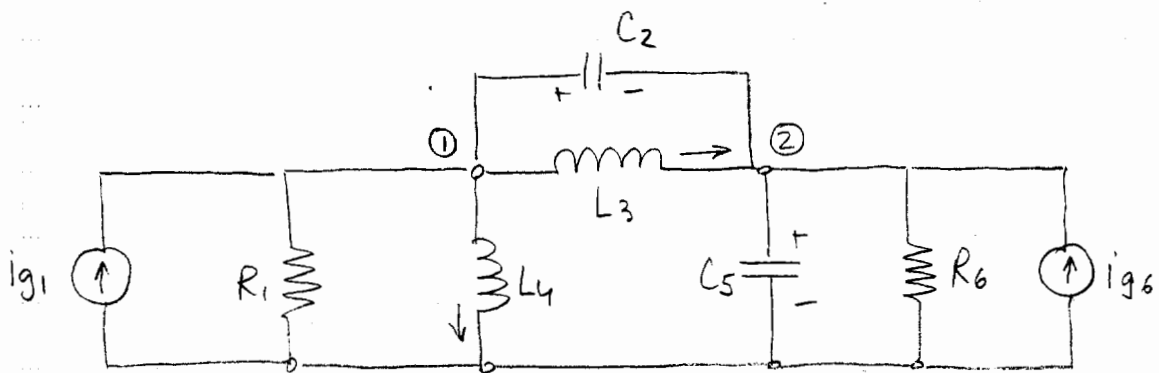
HOMEWORK #4

① For the circuit shown below



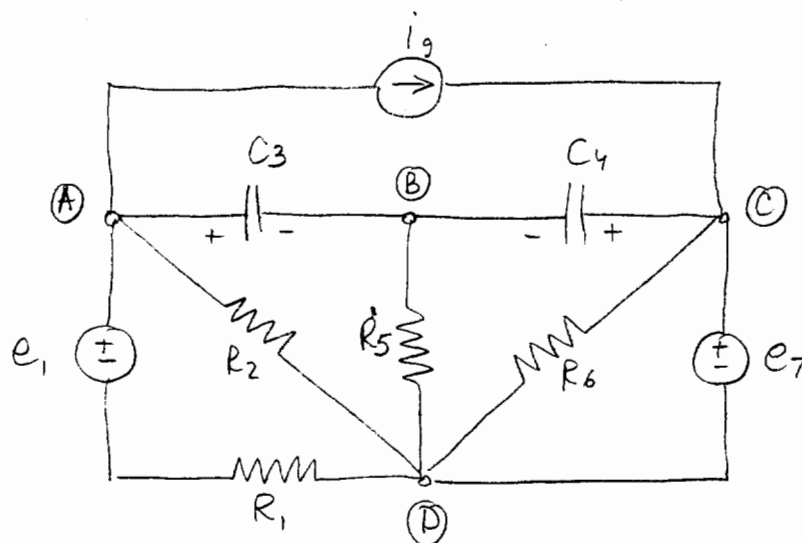
pick the tree that contains the two capacitors and the inductor, and formulate the fundamental loop equations in matrix form

② For the circuit below



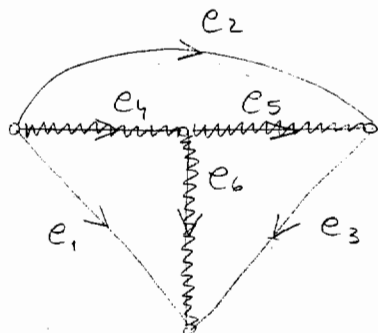
pick a tree that contains inductor L_4 and capacitor C_5 . Then, formulate the fundamental cutset equations.

- ③ Repeat Problem 2 assuming that inductors L_3 and L_4 are coupled. The dot associated with L_4 is at node 1, and the dot for L_3 is at node 2.
- ④ Obtain the fundamental loop equations for the circuit shown below.



SOLUTIONS TO HMWK #4

①



$$B_f = \begin{bmatrix} e_1 & e_2 & e_3 & e_4 & e_5 & e_6 \\ 1 & 0 & 0 & -1 & 0 & -1 \\ 0 & 1 & 0 & -1 & -1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -1 \end{bmatrix}$$

$$V_1(s) = R_1 I_1(s) + E_g(s)$$

$$V_2(s) = R_2 I_2(s)$$

$$V_3(s) = R_6 I_3(s)$$

$$V_4(s) = \frac{1}{sC_3} I_4(s) + \frac{V_{C3}(0)}{s}$$

$$V_5(s) = \frac{1}{sC_4} I_5(s) + \frac{V_{C4}(0)}{s}$$

$$V_6(s) = sL_5 I_6(s) - L_5 i_{L_5}(0)$$

$$Z_e(s) = \begin{bmatrix} R_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & R_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & R_6 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{sC_3} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{sC_4} & 0 \\ 0 & 0 & 0 & 0 & 0 & sL_5 \end{bmatrix}$$

$$\begin{bmatrix} E_g(s) \\ 0 \\ 0 \\ \frac{V_{C3}(0)}{s} \\ \frac{V_{C4}(0)}{s} \\ -L_5 i_{L_5}(0) \end{bmatrix}$$

(2)

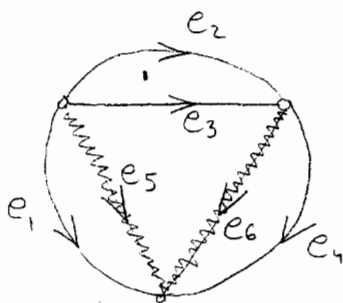
Forming

$$[B_f Z(s) B_f^T] I_2(s) = -B_f \left\{ E e(s) - L e(0) + \frac{1}{s} V e(0) \right\}$$

we obtain

$$\begin{bmatrix} (R_1 + \frac{1}{sC_3} + sL_5) & \frac{1}{sC_3} & sL_5 \\ \frac{1}{sC_3} & (R_2 + \frac{1}{sC_3} + \frac{1}{sC_4}) & -\frac{1}{sC_4} \\ sL_5 & -\frac{1}{sC_4} & (R_6 + \frac{1}{sC_4} + sL_5) \end{bmatrix} \begin{bmatrix} I_1(s) \\ I_2(s) \\ I_3(s) \end{bmatrix} = \begin{bmatrix} -E_g + \frac{V_{c3}(0)}{s} - L_5 I_{L5}(0) \\ \frac{V_{c3}(0)}{s} + \frac{V_{c4}(0)}{s} \\ -\frac{V_{c4}(0)}{s} - L_5 I_{L5}(0) \end{bmatrix}$$

(2)



$$Q_f = \begin{bmatrix} e_1 & e_2 & e_3 & e_4 & e_5 & e_6 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 1 & 0 & 1 \end{bmatrix}$$

$$V_1(s) = R_1 I_1(s) + R_1 I_{g1}(s)$$

$$V_2(s) = \frac{1}{sC_2} I_2(s) + \frac{V_{c2}(0)}{s}$$

$$V_3(s) = sL_3 I_3(s) - L_3 I_{L3}(0)$$

$$V_4(s) = R_6 I_4(s) + R_6 I_{g6}(s)$$

$$V_5(s) = sL_4 I_5(s) - L_4 I_{L4}(0)$$

$$V_6(s) = \frac{1}{sC_5} I_6(s) + \frac{V_{c5}(0)}{s}$$

$$Z_e(s) = \begin{bmatrix} R_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{sC_2} & 0 & 0 & 0 & 0 \\ 0 & 0 & sL_3 & 0 & 0 & 0 \\ 0 & 0 & 0 & R_6 & 0 & 0 \\ 0 & 0 & 0 & 0 & sL_4 & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{sC_5} \end{bmatrix} ; \begin{bmatrix} R_1 I_{g1}(s) \\ V_{c2}(0)/s \\ -L_3 i_{L3}(0) \\ R_6 I_{g6}(s) \\ -L_4 i_{L4}(0) \\ V_{c5}(0)/s \end{bmatrix}$$

The inverse of $Z_e(s)$ is

$$Z_e^{-1}(s) = \begin{bmatrix} \frac{1}{R_1} & 0 & 0 & 0 & 0 & 0 \\ 0 & sC_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{sL_3} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{R_6} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{sL_4} & 0 \\ 0 & 0 & 0 & 0 & 0 & sC_5 \end{bmatrix}$$

Forming

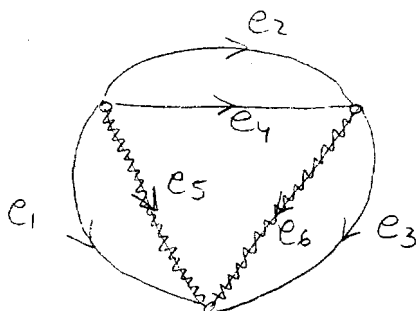
$$[Q_f Z_e^{-1}(s) Q_f^T] V_T(s) = Q_f Z_e^{-1}(s) \{E_e(s) - L_e i_e(0) + \frac{1}{s} V_e(0)\}$$

we have:

$$\begin{bmatrix} (\frac{1}{R_1} + sC_2 + \frac{1}{sL_3} + \frac{1}{sL_4}) & -(sC_2 + \frac{1}{sL_3}) \\ -(sC_2 + \frac{1}{sL_3}) & (sC_2 + \frac{1}{sL_3} + \frac{1}{R_6} + sC_5) \end{bmatrix} \begin{bmatrix} V_5(s) \\ V_6(s) \end{bmatrix} = \begin{bmatrix} I_{g1}(s) + C_2 V_{c2}(0) - \frac{i_{L3}(0)}{s} - \frac{i_{L4}(0)}{s} \\ -C_2 V_{c2}(0) + \frac{i_{L3}(0)}{s} + I_{g6}(s) + C_5 V_{c5}(0) \end{bmatrix}$$

(3)

In this case, it is convenient to number the two inductive branches consecutively (the matrix inversion is easier).



$$Q_f = \begin{bmatrix} e_1 & e_2 & e_3 & e_4 & e_5 & e_6 \\ 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & -1 & 1 & -1 & 0 & 1 \end{bmatrix}$$

$$V_1(s) = R_1 I_1(s) + R_1 I_{g1}(s)$$

$$V_2(s) = \frac{1}{sC_2} I_2(s) + V_{c2}(0)/s$$

$$V_3(s) = R_6 I_3(s) + R_6 I_{g6}(s)$$

$$V_4(s) = sL_3 I_4(s) - L_3 i_{L3}(0) - sM I_5(s) + M i_{L5}(0)$$

$$V_5(s) = sL_4 I_5(s) - L_4 i_{L5}(0) - sM I_4(s) + M i_{L3}(0)$$

$$V_6(s) = \frac{1}{sC_5} I_6(s) + V_{c5}(0)/s$$

$$Z_e(s) = \begin{bmatrix} R_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{sC_2} & 0 & 0 & 0 & 0 \\ 0 & 0 & R_6 & 0 & 0 & 0 \\ 0 & 0 & 0 & sL_3 & -sM & 0 \\ 0 & 0 & 0 & -sM & sL_4 & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{sC_5} \end{bmatrix} ; \begin{bmatrix} R_1 I_{g1}(s) \\ V_{c2}(0)/s \\ R_6 I_{g6}(s) \\ -L_3 i_{L3}(0) + M i_{L5}(0) \\ -L_4 i_{L5}(0) + M i_{L3}(0) \\ V_{c5}(0)/s \end{bmatrix}$$

(5)

Before inverting $Z_e(s)$, we should take advantage of the fact that there is a 2×2 diagonal block in it (this is why consecutive numbering of inductive branches was convenient).

$$\begin{bmatrix} sL_3 & -sM \\ -sM & sL_4 \end{bmatrix}^{-1} = \begin{bmatrix} \frac{L_4}{\Gamma} & \frac{M}{\Gamma} \\ \frac{M}{\Gamma} & \frac{L_3}{\Gamma} \end{bmatrix}$$

where $\Gamma = s(L_3L_4 - M^2)$. Now,

$$Z_e^{-1}(s) = \begin{bmatrix} \frac{1}{R_1} & 0 & 0 & 0 & 0 & 0 \\ 0 & sC_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{R_6} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{L_4}{\Gamma} & -\frac{M}{\Gamma} & 0 \\ 0 & 0 & 0 & -\frac{M}{\Gamma} & \frac{L_3}{\Gamma} & 0 \\ 0 & 0 & 0 & 0 & 0 & sC_5 \end{bmatrix}$$

In this case

$$Q_e Z_e^{-1}(s) = \begin{bmatrix} \frac{1}{R_1} & sC_2 & 0 & \frac{(L_4+M)}{\Gamma} & \frac{(L_3+M)}{\Gamma} & 0 \\ 0 & -sC_2 & \frac{1}{R_6} & -\frac{L_4}{\Gamma} & -\frac{M}{\Gamma} & sC_5 \end{bmatrix}$$

Consequently,

(6)

$$\begin{bmatrix} \left(\frac{1}{R_1} + sC_2 + \frac{L_3 + L_4 + 2M}{\Gamma} \right) & - \left(sC_2 + \frac{L_4 + M}{\Gamma} \right) \\ - \left(sC_2 + \frac{L_4 + M}{\Gamma} \right) & \left(sC_2 + \frac{1}{R_6} + sC_5 + \frac{L_4}{\Gamma} \right) \end{bmatrix} = Q_f Z_e^{-1}(s) Q_f^T$$

The right hand side gets rather messy:

$$RHS = \begin{bmatrix} I_{g1}(s) + C_2 V_{c2}(0) + \left(\frac{L_4 + M}{\Gamma} \right) (-L_3 i_{L3}(0) + M i_{L5}(0)) + \left(\frac{L_3 + M}{\Gamma} \right) (-L_4 i_{L5}(0) + M i_{L3}(0)) \\ -C_2 V_{c2}(0) + I_{g6}(s) - \frac{L_4}{\Gamma} (-L_3 i_{L3}(0) + M i_{L5}(0)) - \frac{M}{\Gamma} (-L_4 i_{L5}(0) + M i_{L3}(0)) + C_5 V_{c5}(0) \end{bmatrix}$$

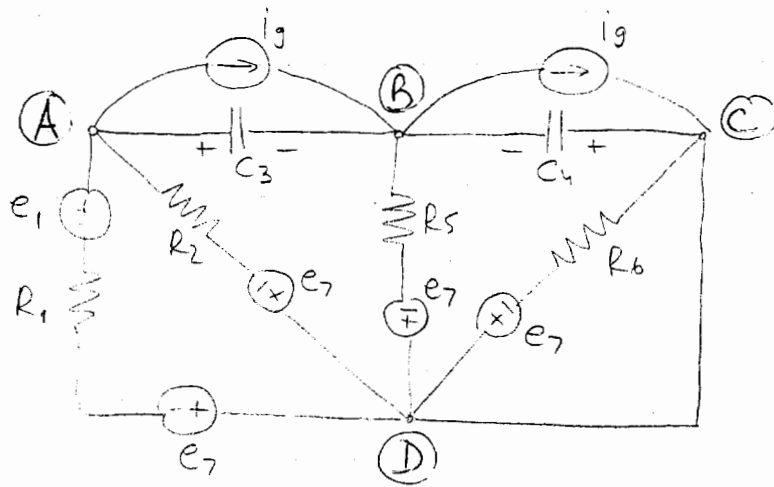
Note, however, that grouping the terms which multiply $i_{L3}(0)$ and $i_{L5}(0)$, and utilizing the fact that $\Gamma \equiv s(L_3 L_4 - M^2)$, the RHS simplifies into:

$$RHS = \begin{bmatrix} I_{g1}(s) + C_2 V_{c2}(0) - \frac{i_{L3}(0)}{s} - \frac{i_{L5}(0)}{s} \\ -C_2 V_{c2}(0) + I_{g6}(s) + \frac{i_{L3}(0)}{s} + C_5 V_{c5}(0) \end{bmatrix}$$

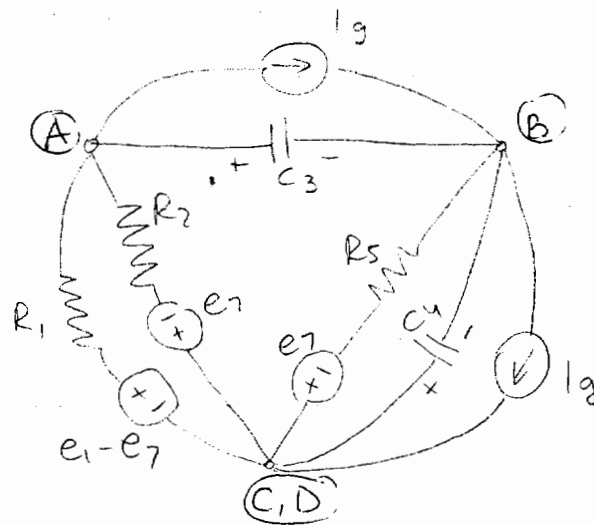
(4)

In this problem it is necessary to perform a transformation of both $e_1(t)$ and $i(t)$.

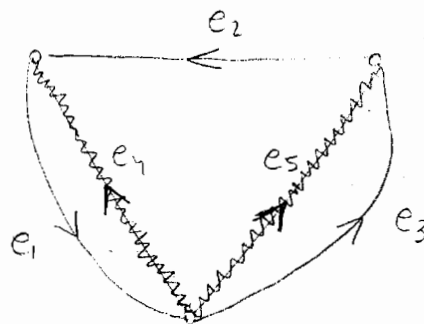
The resulting circuit becomes:



Since nodes C and D are now shorted, the circuit can be redrawn as:



The corresponding graph will be



Note the directions, which are dictated by the sources!

We have:

$$B_f = \begin{bmatrix} e_1 & e_2 & e_3 & e_4 & e_5 \\ 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 & 1 \\ 0 & 0 & 1 & 0 & -1 \end{bmatrix}$$

and

$$V_1(s) = R_1 I_1(s) + E_1(s) - E_7(s)$$

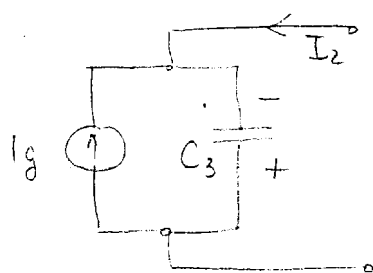
$$V_2(s) = \frac{1}{sC_3} I_2(s) + \frac{1}{sC_3} I_g(s) - \frac{V_{C3}(0)}{s}$$

$$V_3(s) = \frac{1}{sC_4} I_3(s) + \frac{1}{sC_4} I_g(s) + \frac{V_{C4}(0)}{s}$$

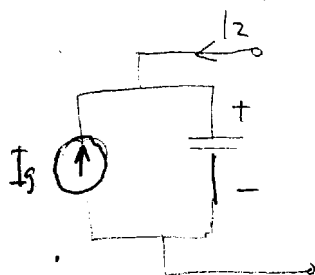
$$V_4(s) = R_2 I_4(s) + E_7(s)$$

$$V_5(s) = R_5 I_5(s) + E_7(s)$$

Note that in $V_2(s)$ we have $-\frac{V_{C3}(0)}{s}$. This is because in this branch:



and our standard expression was derived for the opposite polarity of $V_{C3}(0)$



Consequently,

$$Z_e(s) = \begin{bmatrix} R_1 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{sC_3} & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{sC_4} & 0 & 0 \\ 0 & 0 & 0 & R_2 & 0 \\ 0 & 0 & 0 & 0 & R_5 \end{bmatrix} \begin{bmatrix} E_1(s) - E_7(s) \\ \frac{1}{sC_3} I_g(s) - \frac{V_{C3}(0)}{s} \\ \frac{1}{sC_4} I_g(s) + \frac{V_{C4}(0)}{s} \\ E_7(s) \\ E_7(s) \end{bmatrix}$$

The loop equations can now be written as:

$$\begin{bmatrix} (R_1 + R_2) & -R_2 & 0 \\ -R_2 & (\frac{1}{sC_3} + R_2 + R_5) & -R_5 \\ 0 & -R_5 & (\frac{1}{sC_4} + R_5) \end{bmatrix} \begin{bmatrix} I_1(s) \\ I_2(s) \\ I_3(s) \end{bmatrix} = \begin{bmatrix} -E_1(s) \\ -\frac{1}{sC_3} I_g(s) + \frac{V_{C3}(0)}{s} \\ -\frac{1}{sC_4} I_g(s) - \frac{V_{C4}(0)}{s} + E_7(s) \end{bmatrix}$$