ARM Assembly for Embedded Applications *sth edition* DANIEL W LEWIS

Programming Lab 11A Arithmetic with Reals

Topics: Alternative representations of reals; floating-point hardware & emulation, Q16 fixed-point, posit emulation.

Prerequisite Reading: Chapters 1-11 Revised: June 7, 2021



$$poly(x) = a_0 + a_1x^1 + a_2x^2 + \dots + a_{n-1}x^{n-1}$$

The polynomial is most efficiently evaluated using Horner's method⁴, working backwards from a_{n-1} to a_0 :

$$poly(x) = (((0)x + a_{n-1})x + a_{n-2})x + \dots + a_0$$

Assignment: The main program will compile and run without writing any assembly. However, your task is to create equivalent replacements in assembly language for the following five functions found in the C main program. The original C versions have been defined as "weak" so that the linker will automatically replace them in the executable image by those you create in assembly; you do not need to remove the C versions. This allows you to create and test your assembly language functions one at a time. The five function prototypes share a

common format, but the *function-name* and *data-type* vary. (Note: The code for each of the last three functions should be almost identical.)

data-type function-name(data-type x, data-type a[], int32_t n) ;

<u>function-name</u>	<u>data-type</u>	<u>same as</u>	Implement this function in assembly using
FPH_Poly	float	float	floating-point addition & multiply instructions
Q16_Poly	Q16	int32_t	integer addition & multiply instructions
FPA_Poly	float32_t	int32_t	ASM library functions qfp_fadd & qfp_fmul
FPC_Poly	float32_t	int32_t	C library functions AddFloats & MulFloats
POS_Poly	posit32_t	int32_t	C library functions AddPosits & MulPosits

Download the main program and real-libs.zip. Inside the zip are the *library files* lib1-float.s, lib2-float.c, and lib3-posit.c to be extracted into your src directory together with the C main program. The program calls each of your polynomial functions with an array of n coefficients chosen to approximate the *sine* function at an angle x expressed in radians. Since the approximation of the sine function requires fewer terms near x = 0 for the same accuracy, the main program varies n from 0 to 8 to reduce average execution time. The values returned by your polynomial functions are used to display moving sine waves. If your code is correct, the display should look like the image above although with possibly different cycle counts. Error messages (if any) will appear as white text on a red background.





¹ <u>https://en.wikipedia.org/wiki/Floating-point_arithmetic</u>

² <u>https://en.wikipedia.org/wiki/Fixed-point_arithmetic</u>

³ https://en.wikipedia.org/wiki/Unum (number format)

⁴ <u>https://en.wikipedia.org/wiki/Horner%27s_method</u>